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CURVILINEAR PSEUDOBOOLEAN INTEGRALS

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1. By $\mathbf{B}_2 = \{0,1,\oplus, \cdot\}$ we write the binary Boole algebra, where ' \oplus ' is the modulo 2 sum and ' \cdot ' is the intersection. If $\{a_i \mid i \in I\}$ is a binary family so that it has a finite support

$$|\{i \mid i \in I, a_i = 1\}| < \infty$$

then it makes sense to speak about the modulo 2 summation of the elements of this family, that will be written $\Xi_{i \in I} a_i$. In fact,

$$\Xi_{i \in I} a_i = \begin{cases} 1, & \text{if } |\{i \mid i \in I, a_i = 1\}| = 2k + 1 \\ 0, & \text{if } |\{i \mid i \in I, a_i = 1\}| = 2k \end{cases}$$

If $I = \mathbf{N}$, then the meaning of this sum is that of a convergent series. If the support of this family to be summed is not finite, then the sum cannot be done and this is the sense of a divergent series in this theory.

The topology of \mathbf{B}_2 is the discrete one.

2. Let $x : [a, b] \rightarrow \mathbf{B}_2$ with the property that the set $\{t \mid t \in [a, b], x(t) = 1\}$ is finite. The *left integral* and the *right integral* of x on $[a, b]$, respectively on (a, b) is given by:

$$\int_a^b x = \Xi_{\xi \in [a, b]} x(\xi), \int_a^{b^*} x = \Xi_{\xi \in (a, b)} x(\xi)$$

3. A function $x : [a, b] \rightarrow \mathbf{B}_2$ has *left limits* if

$$\forall t \in (a, b), \exists x(t-0) \in \mathbf{B}_2, \exists \varepsilon > 0, \forall \xi \in (t - \varepsilon, t) \wedge (a, b), x(\xi) = x(t-0)$$

and, in a dual way, x has *right limits* if

$$\forall t \in [a, b), \exists x(t+0) \in \mathbf{B}_2, \exists \varepsilon > 0, \forall \xi \in (t, t + \varepsilon) \wedge [a, b), x(\xi) = x(t+0)$$

In the case that these properties are true, there are defined the functions $x(t-0)$ and $x(t+0)$ called the *left limit* and the *right limit function* of x .

4. Let $x : [a, b] \rightarrow \mathbf{B}_2$ be with left limits and right limits (not equal, in general). In such cases, we ask that in the points a and b , x has a right limit, respectively a left limit. The functions:

$$Dx(t) = x(t-0) \oplus x(t), D^*x(t) = x(t+0) \oplus x(t)$$

are called the *left derivative* and the *right derivative* of x .

5. **Lemma** If $x : [a, b] \rightarrow \mathbf{B}_2$ has left limits and right limits, then the sets

$$\{t \mid t \in (a, b), Dx(t) = 1\}, \{t \mid t \in [a, b), D^*x(t) = 1\}$$

are finite.

Proof From the definition of the left limits and of the right limits, we have the existence of a set of points

$$a = t_0 < t_1 < \dots < t_n = b$$

with the property that

$$\forall i \in \{1, \dots, n\}, \forall \xi, \xi' \in (t_{i-1}, t_i), x(\xi) = x(\xi')$$

and finally

$$\{t \mid t \in (a, b), Dx(t) = 1\} \subset \{t_1, \dots, t_n\}, \{t \mid t \in [a, b), D^*x(t) = 1\} \subset \{t_0, \dots, t_{n-1}\}$$

6. Remark The previous definition 3 may be extended at $[a, b] \rightarrow \mathbf{B}_2^n$ functions, $n \geq 1$. In the paper, we shall consider the case $n = 2$.

7. A *path* in \mathbf{B}_2^2 is a function $\gamma: [a, b] \rightarrow \mathbf{B}_2^2$, $\gamma = (\gamma_1, \gamma_2)$, that has left limits and right limits. The path is called *closed* if $\gamma(a) = \gamma(b)$.

The *inverse* of γ is defined to be the path $\gamma^-: [a, b] \rightarrow \mathbf{B}_2^2$,

$$\gamma^-(t) = \gamma(a + b - t)$$

The *reunion* of the paths $\gamma: [a, b] \rightarrow \mathbf{B}_2^2$, $\sigma: [b, c] \rightarrow \mathbf{B}_2^2$ that satisfy $\gamma(b) = \sigma(b)$ is defined by

$$\gamma \vee \sigma: [a, c] \rightarrow \mathbf{B}_2^2, (\gamma \vee \sigma)(t) = \begin{cases} \gamma(t), & t \in [a, b] \\ \sigma(t), & t \in [b, c] \end{cases}$$

The *equivalence* of the paths $\gamma: [a, b] \rightarrow \mathbf{B}_2^2$ and $\sigma: [c, d] \rightarrow \mathbf{B}_2^2$ is written $\gamma \sim \sigma$ and is given by the existence of an increasing homeomorphism $h: [a, b] \rightarrow [c, d]$ so that the next diagram is commutative:

$$\begin{array}{ccc} [a, b] & \xrightarrow{h} & [c, d] \\ \gamma \searrow & & \swarrow \sigma \\ & \mathbf{B}_2^2 & \end{array}$$

8. It is called *Boolean form* on \mathbf{B}_2^2 a function $\omega: \mathbf{B}_2^2 \rightarrow F(\mathbf{B}_2^2, \mathbf{B}_2)$ where we have noted

$$F(\mathbf{B}_2^2, \mathbf{B}_2) = \{f \mid f: \mathbf{B}_2^2 \rightarrow \mathbf{B}_2\}$$

so that for any $x, y \in \mathbf{B}_2^2$, $x = (x_1, x_2)$, $y = (y_1, y_2)$, ω is given by:

$$\omega(x)(y) = \omega_1(x) \cdot y_1 \oplus \omega_2(x) \cdot y_2 \oplus \omega_3(x) \cdot y_1 \cdot y_2$$

We just mention that with the notation

$$F(\mathbf{B}_2^n, \mathbf{B}_2) = \{f \mid f: \mathbf{B}_2^n \rightarrow \mathbf{B}_2\}$$

the Boolean forms on \mathbf{B}_2^n are functions $\mathbf{B}_2^n \rightarrow F(\mathbf{B}_2^n, \mathbf{B}_2)$.

9. Let the Boolean form ω on \mathbf{B}_2^2 and $\gamma: [a, b] \rightarrow \mathbf{B}_2^2$ be a path. Because the sets

$$\{t \mid t \in (a, b), \omega_1(\gamma(t)) \cdot D\gamma_1(t) = 1\}, \{t \mid t \in [a, b), \omega_1(\gamma(t)) \cdot D^*\gamma_1(t) = 1\}$$

$$\{t \mid t \in (a, b), \omega_2(\gamma(t)) \cdot D\gamma_2(t) = 1\}, \{t \mid t \in [a, b), \omega_2(\gamma(t)) \cdot D^*\gamma_2(t) = 1\}$$

$$\{t \mid t \in (a, b), \omega_3(\gamma(t)) \cdot D\gamma_1(t) \cdot D\gamma_2(t) = 1\}, \{t \mid t \in [a, b), \omega_3(\gamma(t)) \cdot D^*\gamma_1(t) \cdot D^*\gamma_2(t) = 1\}$$

are finite – accordingly to lemma 5- there has sense the number

$$\int_{\gamma} \omega = \int_a^b \omega_1(\gamma) \cdot D^* \gamma_1 \oplus \int_a^b \omega_2(\gamma) \cdot D^* \gamma_2 \oplus \int_a^b \omega_3(\gamma) \cdot D^* \gamma_1 \cdot D^* \gamma_2 \oplus$$

$$\oplus \int_a^{b^*} \omega_1(\gamma) \cdot D\gamma_1 \oplus \int_a^{b^*} \omega_2(\gamma) \cdot D\gamma_2 \oplus \int_a^{b^*} \omega_3(\gamma) \cdot D\gamma_1 \cdot D\gamma_2$$

all the six integrals from the right side being defined. It is called the *curvilinear integral of ω along the path γ* .

10. **Theorem** a) If $\gamma \sim \sigma$, then

$$\int_{\gamma} \omega = \int_{\sigma} \omega$$

b) If $\gamma \vee \sigma$ makes sense, then

$$\int_{\gamma \vee \sigma} \omega = \int_{\gamma} \omega \oplus \int_{\sigma} \omega$$

c)

$$\int_{\gamma} \omega = \int_{\gamma^-} \omega.$$

Proof a) Let $\gamma : [a, b] \rightarrow \mathbf{B}_2^2$ and $\sigma : [c, d] \rightarrow \mathbf{B}_2^2$ be two paths for which there exists the increasing homeomorphism $h : [a, b] \rightarrow [c, d]$ with the property that it makes commutative the diagram:

$$\begin{array}{ccc} [a, b] & \xrightarrow{h} & [c, d] \\ \searrow \gamma & & \swarrow \sigma \\ & \mathbf{B}_2^2 & \end{array}$$

The fact that there takes place

$$\int_a^{b^*} \omega_1(\gamma) \cdot D\gamma_1 = \int_c^{d^*} \omega_1(\sigma) \cdot D\sigma_1$$

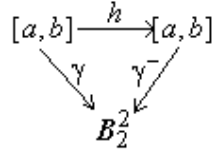
for example may be shown by taking into account the following equivalences, where to $u, u', u'' \in (a, b)$ there uniquely correspond the points $v = h(u), v' = h(u'), v'' = h(u'') \in (c, d)$:

$$\begin{aligned} \omega_1(\gamma(u)) \cdot D\gamma_1(u) = 1 &\Leftrightarrow \exists u' \in (a, u), \forall u'' \in (u', u), \omega_1(\gamma(u)) \cdot (\gamma_1(u'') \oplus \gamma_1(u)) = 1 \\ &\Leftrightarrow \exists v' \in (c, v), \forall v'' \in (v', v), \omega_1(\sigma(v)) \cdot (\sigma_1(v'') \oplus \sigma_1(v)) = 1 \Leftrightarrow \omega_1(\sigma(v)) \cdot D\sigma_1(v) = 1 \end{aligned}$$

b) We remark that if $\gamma : [a, b] \rightarrow \mathbf{B}_2^2$ and $\sigma : [b, c] \rightarrow \mathbf{B}_2^2$ there take place the formulas that are symbolized by:

$$\int_a^c = \int_a^b \oplus \int_b^c, \int_a^{c^*} = \int_a^{b^*} \oplus \int_b^{c^*}$$

c) We have $\gamma, \gamma^- : [a, b] \rightarrow \mathbf{B}_2^2$ and the decreasing homeomorphism $h : [a, b] \rightarrow [a, b]$ that is given by $h(t) = a + b - t$ and makes commutative the diagram:



Analogously to the situation from item a), we can show that for any $u, v \in (a, b)$, $v = h(u)$, it is true for example the equation:

$$\omega_1(\gamma(u)) \cdot D^* \gamma_1(u) = \omega_1(\gamma^-(v)) \cdot D\gamma_1^-(v)$$

This is also the case if $u = a$, $v = b$ and we can write:

$$\begin{aligned} \int_a^b \omega_1(\gamma) \cdot D^* \gamma_1 &= \Xi_{u \in [a, b]} \omega_1(\gamma(u)) \cdot D^* \gamma_1(u) = \Xi_{u \in (a, b)} \omega_1(\gamma(u)) \cdot D^* \gamma_1(u) \oplus \omega_1(\gamma(a)) \cdot D^* \gamma_1(a) = \\ &= \Xi_{v \in (a, b)} \omega_1(\gamma^-(v)) \cdot D\gamma_1^-(v) \oplus \omega_1(\gamma^-(b)) \cdot D\gamma_1^-(b) \\ &= \Xi_{v \in (a, b]} \omega_1(\gamma^-(v)) \cdot D\gamma_1^-(v) = \int_a^b \omega_1(\gamma^-) \cdot D\gamma_1^- \end{aligned}$$

The other equations may be proved similarly.

11. Let $\omega: \mathbf{B}_2^2 \rightarrow F(\mathbf{B}_2^2, \mathbf{B}_2)$ be a Boolean form. It is called *exact* if there exists $f: \mathbf{B}_2^2 \rightarrow \mathbf{B}_2$ with the property that:

$$\forall x \in \mathbf{B}_2^2, \partial_1 f(x) = \omega_1(x), \partial_2 f(x) = \omega_2(x), \partial_{12}^2 f(x) = \omega_3(x)$$

where ∂ is the notation for the *Boolean derivative*

$$\begin{aligned} \partial_1 f(x_1, x_2) &= f(x_1 \oplus 1, x_2) \oplus f(x_1, x_2) \\ \partial_2 f(x_1, x_2) &= f(x_1, x_2 \oplus 1) \oplus f(x_1, x_2) \\ \partial_{12}^2 f(x_1, x_2) &= \partial_1(\partial_2 f(x_1, x_2)) = \partial_2(\partial_1 f(x_1, x_2)) \end{aligned}$$

12. **Remark** The functions $f: \mathbf{B}_2^2 \rightarrow \mathbf{B}_2$ may be put under the form

$$f(x_1, x_2) = a \oplus b \cdot x_1 \oplus c \cdot x_2 \oplus d \cdot x_1 \cdot x_2$$

where $a, b, c, d \in \mathbf{B}_2$ and then, if ω is exact, it is given – after following an identification procedure – by:

$$\begin{aligned} \omega_1(x_1, x_2) &= b \oplus d \cdot x_2 \\ \omega_2(x_1, x_2) &= c \oplus d \cdot x_1 \\ \omega_3(x_1, x_2) &= d \end{aligned}$$

It is seen the validity of the formula:

$$\partial_2 \omega_1(x_1, x_2) = \partial_1 \omega_2(x_1, x_2) (= d)$$

recalling the theory of the real functions (the closed real differentiable forms).

Conversely, if $\omega_1, \omega_2, \omega_3$ are like above, then ω is exact.

13. **Theorem** The next statements are equivalent:

- ω is exact
- for any closed path $\gamma: [a, b] \rightarrow \mathbf{B}_2^2$, we have

$$\int_{\gamma} \omega = 0$$

c) for any paths $\gamma: [a, b] \rightarrow \mathbf{B}_2^2$, $\sigma: [c, d] \rightarrow \mathbf{B}_2^2$ with the same extremes $\gamma(a) = \sigma(c)$, $\gamma(b) = \sigma(d)$ we have:

$$\int_{\gamma} \omega = \int_{\sigma} \omega$$

Proof a) \Rightarrow b) There are two lemmas that we need.

14. **Lemma** Being given $f: \mathbf{B}_2^2 \rightarrow \mathbf{B}_2$ and the function $\gamma: (a, b] \rightarrow \mathbf{B}_2^2$ with left limits, there takes place the formula:

$$Df(\gamma_1(t), \gamma_2(t)) = \partial_1 f(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_1(t) \oplus \\ \oplus \partial_2 f(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_2(t) \oplus \partial_{12}^2 f(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_1(t) \cdot D\gamma_2(t)$$

This fact may be seen from the following equalities, that are valid for any

$a, b, c, d, x_1, x_2, y_1, y_2 \in \mathbf{B}_2$:

$$f(x_1, x_2) = a \oplus b \cdot x_1 \oplus c \cdot x_2 \oplus d \cdot x_1 \cdot x_2 \\ \partial_1 f(x_1, x_2) = b \oplus d \cdot x_2, \partial_2 f(x_1, x_2) = c \oplus d \cdot x_1 \\ \partial_{12}^2 f(x_1, x_2) = d$$

$$\Rightarrow f(x_1, x_2) \oplus f(y_1, y_2) = \partial_1 f(x_1, x_2) \cdot (y_1 \oplus x_1) \oplus \partial_2 f(x_1, x_2) \cdot (y_2 \oplus x_2) \oplus \\ \oplus \partial_{12}^2 f(x_1, x_2) \cdot (y_1 \oplus x_1) \cdot (y_2 \oplus x_2)$$

(identity easy to remark). Furthermore, by considering

$$(x_1, x_2) = (\gamma_1(t), \gamma_2(t)) \\ (y_1, y_2) = (\gamma_1(t-0), \gamma_2(t-0))$$

the statement of the lemma results.

15. **Lemma** Let $x: [a, b] \rightarrow \mathbf{B}_2$ with left limits and right limits. It is true the formula of Leibniz-Newton:

$$\int_a^b D^* x \oplus \int_a^b D x = x(a) \oplus x(b)$$

Proof Let the points

$$a = t_0 < t_1 < \dots < t_n = b$$

like in the proof of lemma 5, defined by the property that the values $c_0, c_1, \dots, c_n, d_1, \dots, d_n \in \mathbf{B}_2$ exist so that

$$x(t_i) = c_i, i = \overline{0, n} \\ \forall \xi \in (t_i, t_{i+1}), x(\xi) = d_{i+1}, i = \overline{0, n-1}$$

We see that

$$\int_a^b D^* x \oplus \int_a^b D x = (c_0 \oplus d_1) \oplus (c_1 \oplus d_2) \oplus \dots \oplus (c_{n-1} \oplus d_n) \oplus \\ \oplus (d_1 \oplus c_1) \oplus (d_2 \oplus c_2) \oplus \dots \oplus (d_n \oplus c_n) = c_0 \oplus c_n = x(a) \oplus x(b)$$

We may proceed now to prove the implication a) \Rightarrow b) and from the hypothesis there exists a function $f: \mathbf{B}_2^2 \rightarrow \mathbf{B}_2$ with the property that

$$\forall x \in \mathbf{B}_2^2, \partial_1 f(x) = \omega_1(x), \partial_2 f(x) = \omega_2(x), \partial_{12}^2 f(x) = \omega_3(x)$$

We take some path $\gamma:[a,b] \rightarrow \mathbf{B}_2^2$ with the property that $\gamma(a) = \gamma(b)$. We may write, by using lemma 14 and its right dual:

$$\begin{aligned} Df(\gamma_1(t), \gamma_2(t)) &= \partial_1 f(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_1(t) \oplus \\ &\oplus \partial_2 f(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_2(t) \oplus \partial_{12}^2 f(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_1(t) \cdot D\gamma_2(t) = \\ &= \omega_1(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_1(t) \oplus \omega_2(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_2(t) \oplus \omega_3(\gamma_1(t), \gamma_2(t)) \cdot D\gamma_1(t) \cdot D\gamma_2(t) \\ D^* f(\gamma_1(t), \gamma_2(t)) &= \omega_1(\gamma_1(t), \gamma_2(t)) \cdot D^* \gamma_1(t) \oplus \omega_2(\gamma_1(t), \gamma_2(t)) \cdot D^* \gamma_2(t) \oplus \\ &\oplus \omega_3(\gamma_1(t), \gamma_2(t)) \cdot D^* \gamma_1(t) \cdot D^* \gamma_2(t) \end{aligned}$$

and from lemma 15:

$$\int_{\gamma} \omega = \int_a^b D^* f(\gamma) \oplus \int_a^{b^*} Df(\gamma) = f(\gamma(a)) \oplus f(\gamma(b)) = 0$$

b) \Rightarrow c) Let us take $\gamma:[c,d] \rightarrow \mathbf{B}_2^2$ and $\sigma:[c',d'] \rightarrow \mathbf{B}_2^2$ two paths satisfying the conditions:
 $\gamma(c) = \sigma(c'), \gamma(d) = \sigma(d')$

We fix $a < b$ and $a' \in (a,b)$ and choose the increasing homeomorphism $h_1:[a,a'] \rightarrow [c',d']$ respectively the decreasing homeomorphism $h_2:[a',b] \rightarrow [c',d']$ that give the definitions

$$\begin{aligned} \alpha_1:[a,a'] &\rightarrow \mathbf{B}_2^2, \alpha_1 \stackrel{def}{=} \gamma \circ h_1 \\ \alpha_2:[a',b] &\rightarrow \mathbf{B}_2^2, \alpha_2 \stackrel{def}{=} \sigma \circ h_2 \end{aligned}$$

The reunion $\alpha = \alpha_1 \vee \alpha_2:[a,b] \rightarrow \mathbf{B}_2^2$ makes sense because

$$\alpha_1(a') = (\gamma \circ h_1)(a') = \gamma(d) = \sigma(d') = (\sigma \circ h_2)(a') = \alpha_2(a')$$

and it is a closed path

$$\alpha(a) = \alpha_1(a) = (\gamma \circ h_1)(a) = \gamma(c) = \sigma(c') = (\sigma \circ h_2)(b) = \alpha_2(b) = \alpha(b)$$

By making use of the hypothesis, as well as of the fact that $\alpha_1 \sim \gamma, \alpha_2^- \sim \sigma$, we have:

$$0 = \int_{\alpha_1 \vee \alpha_2} \omega = \int_{\alpha_1} \omega \oplus \int_{\alpha_2} \omega = \int_{\alpha_1} \omega \oplus \int_{\alpha_2^-} \omega = \int_{\gamma} \omega \oplus \int_{\sigma} \omega$$

c) \Rightarrow a) Let us put ω under the form:

$$\omega_i(x_1, x_2) = a_i \oplus b_i \cdot x_1 \oplus c_i \cdot x_2 \oplus d_i \cdot x_1 \cdot x_2$$

where $a_i, b_i, c_i, d_i \in \overline{\mathbf{B}_2}, i = \overline{1,3}$ and we show, by choosing convenient pairs of paths

$\gamma, \sigma:[a,b] \rightarrow \mathbf{B}_2^2$ with the same extremes: $\gamma(a) = \sigma(a), \gamma(b) = \sigma(b)$ that ω is of the same form like the one indicated in Remark 12. We shall use the notation $\chi_{(\cdot)}:[a,b] \rightarrow \mathbf{B}_2$ for the characteristic function and let $\tau \in (a,b)$;

$$\gamma = (\chi_{(\tau,b]}, 0)$$

$$\sigma = (\chi_{[\tau,b]}, 0)$$

give, because the only non-zero derivatives are $D^* \gamma_1 = \chi_{\{\tau\}}, D\sigma_1 = \chi_{\{\tau\}}$,

$$\int_{\gamma} \omega = \omega_1(\gamma(\tau)) = a_1, \int_{\sigma} \omega = \omega_1(\sigma(\tau)) = a_1 \oplus b_1$$

so that $a_1 = a_1 \oplus b_1$ and $b_1 = 0$.

This reasoning was written in table 1.

γ	σ	The equation	The conclusions	Remarks
$(\chi_{(\tau,b)},0)$	$(\chi_{[\tau,b]},0)$	$a_1 = a_1 \oplus b_1$	$b_1 = 0$	(1)
$(0,\chi_{(\tau,b)})$	$(0,\chi_{[\tau,b]})$	$a_2 = a_2 \oplus c_2$	$c_2 = 0$	(2)
$(\chi_{(\tau,b)},1)$	$(\chi_{[\tau,b]},1)$	$a_1 \oplus c_1 = a_1 \oplus b_1 \oplus c_1 \oplus d_1$	$d_1 = 0$	(3) from (1)
$(1,\chi_{(\tau,b)})$	$(1,\chi_{[\tau,b]})$	$a_2 \oplus b_2 = a_2 \oplus b_2 \oplus c_2 \oplus d_2$	$d_2 = 0$	(4) from (2)
$(\chi_{(\tau,b)},\chi_{(\tau,b)})$	$(\chi_{[\tau,b]},\chi_{[\tau,b]})$	$a_1 \oplus a_2 \oplus a_3 = a_1 \oplus c_1 \oplus a_2 \oplus b_2 \oplus a_3 \oplus b_3 \oplus c_3 \oplus d_3$	$c_1 \oplus b_2 \oplus b_3 \oplus c_3 \oplus d_3 = 0$	(5)
$(\chi_{[a,\tau]},\chi_{[a,\tau]})$	$(\chi_{[a,\tau]},\chi_{[a,\tau]})$	$a_1 \oplus c_1 \oplus a_2 \oplus b_2 \oplus a_3 \oplus b_3 \oplus c_3 \oplus d_3 = a_1 \oplus c_1 \oplus a_2$	$b_2 \oplus a_3 \oplus b_3 \oplus c_3 \oplus d_3 = 0$	(6)
			$c_1 = a_3$	(7) from (5), (6)
$(\chi_{[a,\tau]},\chi_{[a,\tau]})$	$(\chi_{[a,\tau]},\chi_{[a,\tau]})$	$a_1 \oplus c_1 \oplus a_2 \oplus b_2 \oplus a_3 \oplus b_3 \oplus c_3 \oplus d_3 = a_1 \oplus a_2 \oplus b_2$	$c_1 \oplus a_3 \oplus b_3 \oplus c_3 \oplus d_3 = 0$	(8)
			$b_2 = a_3$	(9) from (5),(8)
			$c_1 = b_2$	(10) from (7),(9)
			$b_3 \oplus c_3 \oplus d_3 = 0$	(11) from (6),(9)
$(\chi_{[a,\tau]},\chi_{[\tau,b]})$	$(\chi_{[a,\tau]},\chi_{[\tau,b]})$	$a_1 \oplus c_1 \oplus a_2 \oplus a_3 \oplus c_3 = a_1 \oplus a_2 \oplus b_2 \oplus a_3 \oplus b_3$	$c_1 \oplus c_3 \oplus b_2 \oplus b_3 = 0$	(12)
			$b_3 = c_3$	(13) from (10),(12)
			$d_3 = 0$	(14) from (11),(13)
$(\chi_{[a,\tau] \vee (\nu,b)},\chi_{[\tau,b]})$	$(1,\chi_{[\tau,b]})$	$a_1 \oplus c_1 \oplus a_2 \oplus c_2 \oplus a_3 \oplus c_3 \oplus a_1 \oplus c_1 = a_2 \oplus b_2$	$a_3 \oplus c_3 \oplus b_2 = 0$	(15) $a < \tau < \nu < b$ from (2)
			$c_3 = b_3 = 0$	(16) from (9),(13),(15)

Table 1